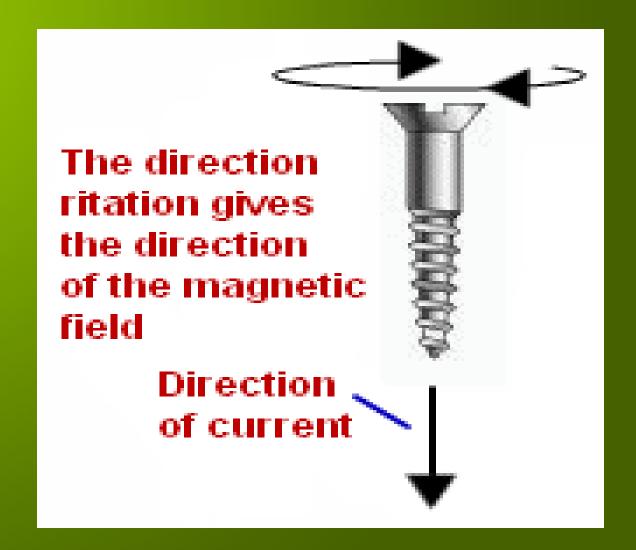




Maxwell's Cork screw Rule:





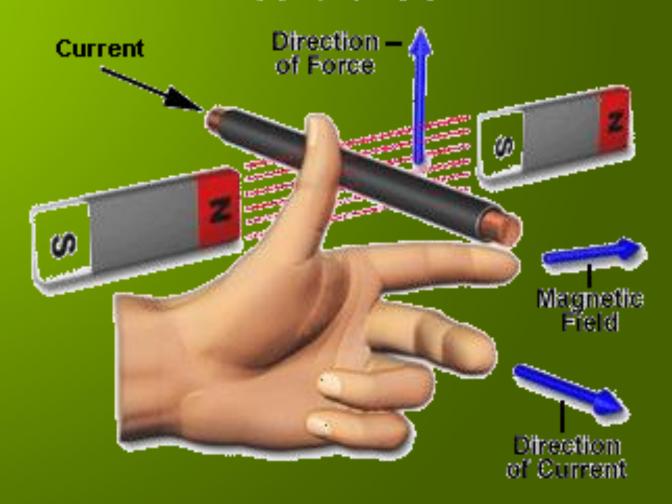
Maxwell's Cork screw Rule:

Hold the cork screw in yr right hand and rotate it in clockwise in such a way that it advances in the direction of current. Then the direction in which the hand rotates will be the direction of magnetic lines of force.



Fleming's left hand rule

Left Hand Rule





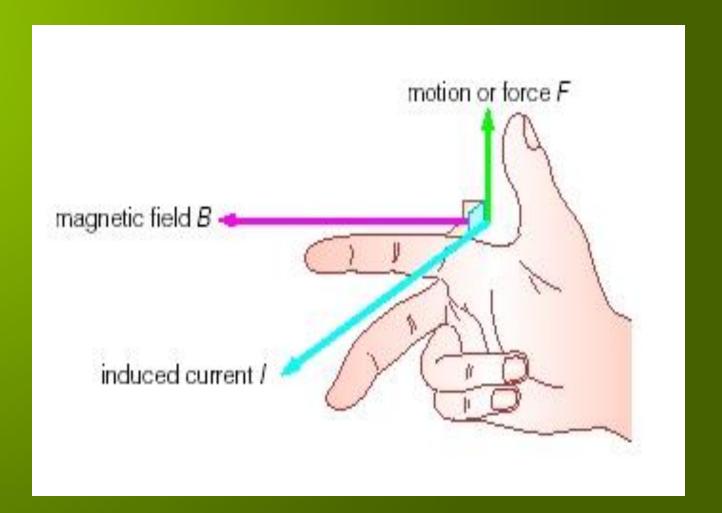
Fleming's left hand rule

- Used to determine the <u>direction of force acting</u> on a current carrying conductor placed in a magnetic field.
- The middle finger, the fore finger and thumb of the left hand are kept at right angles to one another.
- ► The middle finger represent the direction of current
- The fore finger represent the direction of magnetic field
- The thumb will indicate the direction of force acting on the conductor .

This rule is used in motors.



Fleming's Right hand rule





Fleming's Right hand rule

- Used to determine the direction of emf induced in a conductor
- ► The middle finger, the fore finger and thumb of the left hand are kept at right angles to one another.
 - ►The fore finger represent the direction of magnetic field
 - ▶The thumb represent the direction of motion of the conductor
 - The middle finger will indicate the direction of the inducted emf.

This rule is used in DC Generators



Len's Law

The direction of induced emf is given by Lenz's law.

According to this law, the induced emf will be acting in such a way so as to oppose the very cause of production of it.

 $e = -N (d\emptyset/dt) \text{ volts}$

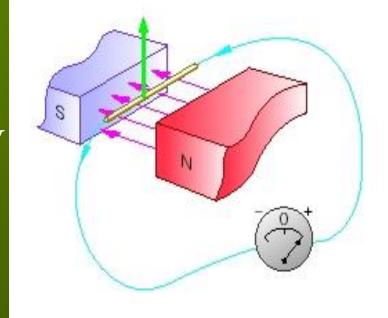


DC Generator

Mechanical energy is converted to electric energy

Three requirements are essential

- 1. Conductors
- 2. Magnetic field
- 3. Mechanical energy

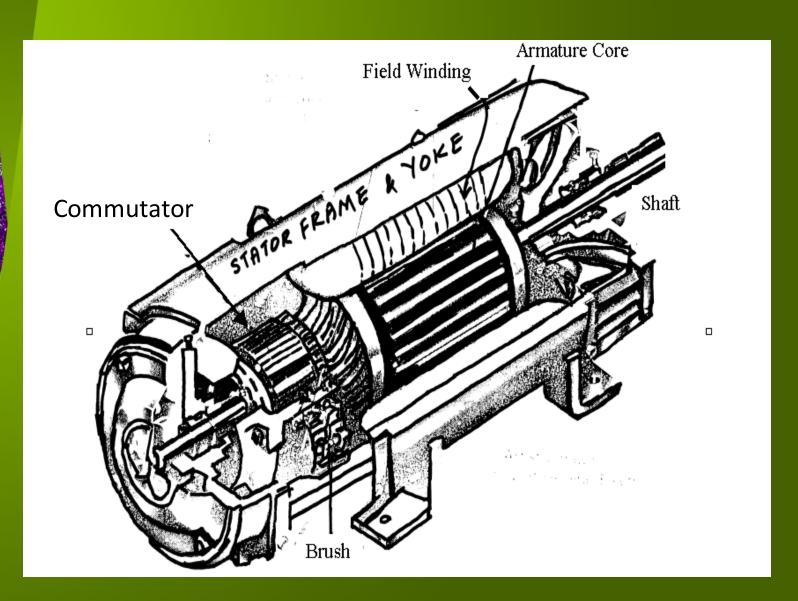




Working principle

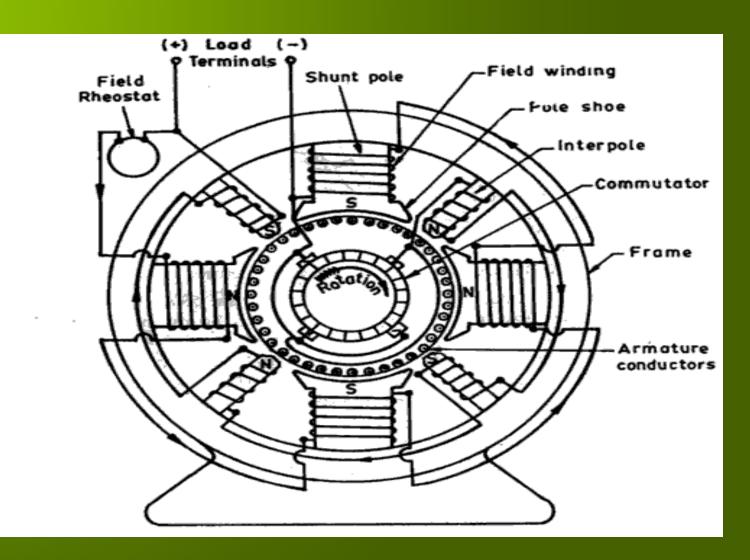
- ► A generator works on the principles of Faraday's law of electromagnetic induction
- Whenever a conductor is moved in the magnetic field, an emf is induced and the magnitude of the induced emf is directly proportional to the rate of change of flux linkage.
- ► This emf causes a current flow if the conductor circuit is closed .

DC Machine



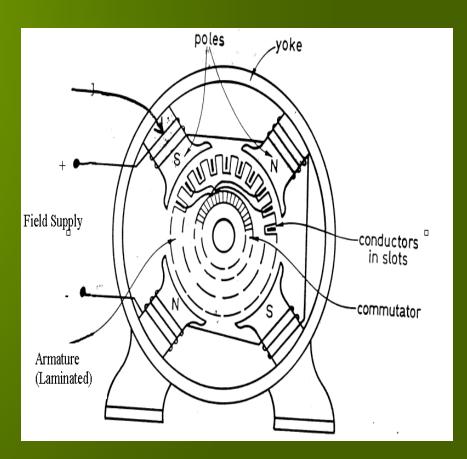


Sectional view of a DC machine





- Field system
- Armature core
- Armature winding
- Commutator
- Brushes

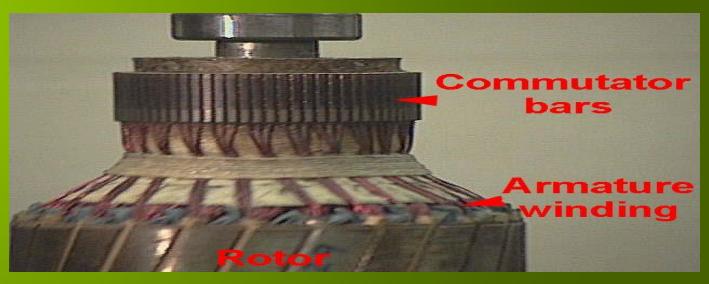


Field winding



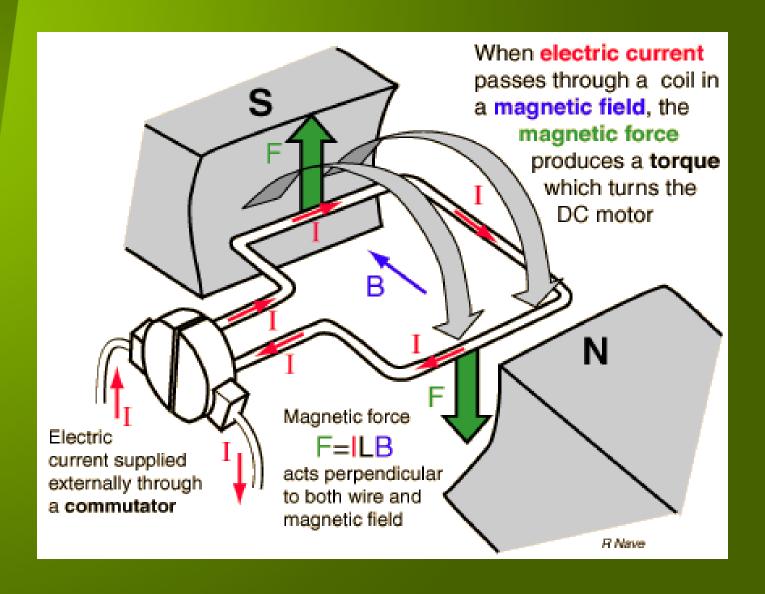


Rotor and rotor winding





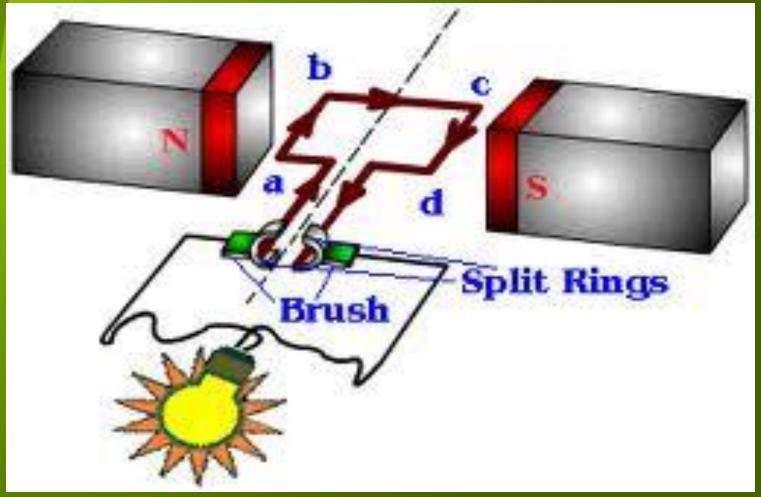
Working principle of DC motor



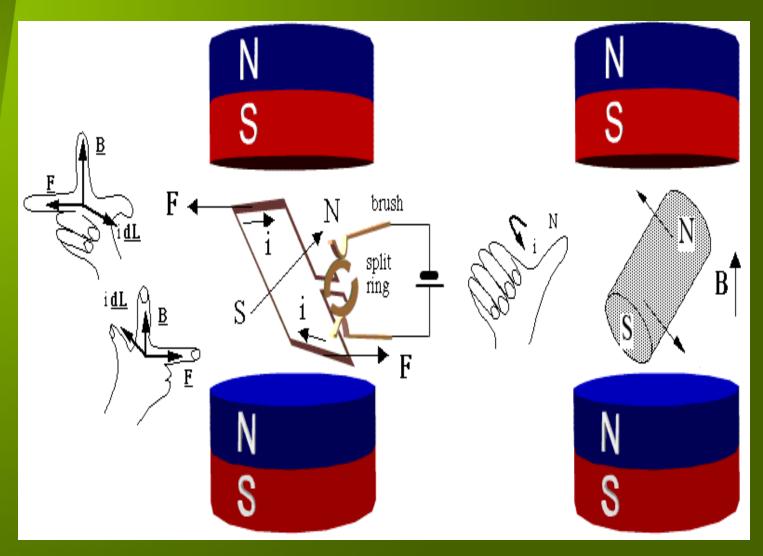




Working principle of DC motor



Force in DC motor





Armature winding

There are 2 types of winding Lap and Wave winding

Lap winding

► A = P

The armature windings are divided into no. of sections equal to the no of poles

Wave winding

► A = 2

- It is used in low current output and high voltage.
- 2 brushes



Field system

- ►It is for uniform magnetic field within which the armature rotates.
- ► Electromagnets are preferred in comparison with permanent magnets
- ►They are cheap, smaller in size, produce greater magnetic effect and
- Field strength can be varied



Field system consists of the following parts

- **▶**Yoke
- ▶Pole cores
- ▶Pole shoes
- Field coils



Armature core

- ▶The armature core is cylindrical
- High permeability silicon steel stampings
- ► Impregnated
- Lamination is to reduce the eddy current loss



Commutator

- Connect with external circuit
- Converts ac into unidirectional current
- 👚 Cylindrical in shape
- Made of wedge shaped copper segments
- Segments are insulated from each other
- Each commutator segment is connected to armature conductors by means of a cu strip called riser.
- No of segments equal to no of coils



Carbon brush

- Carbon brushes are used in DC machines because they are soft materials
- ★It does not generate spikes when they contact commutator
- **★**To deliver the current thro armature
- Carbon is used for brushes because it has negative temperature coefficient of resistance
- Self lubricating , takes its shape , improving area of contact



Brush rock and holder





Carbon brush

- ▶Brush leads (pig tails)
- Brush rocker (brush gear)
- Front end cover
- ▶Rear end cover
- **▶**Cooling fan
- **▶**Bearing
- ▶Terminal box



Flux cut by 1 conductor = P * ф in 1 revolution Flux cut by 1 conductor in $= P \phi N / 60$ 60 sec Avg emf generated in 1 $= P\phi N/60$ conductor Number of conductors in each parallel path = Z/A

 $= P\phi NZ/60A$



Types of DC Generator

DC generators are generally classified according to their method of excitation.

Separately excited DC generator

Self excited D C generator

Further classification of DC Generator

- Series wound generator
- Shunt wound generator
- Compound wound generator
 - Short shunt & Long shunt
 - Cumulatively compound

&

Differentially compound

Losses in DC Generators

- 1. Copper losses or variable losses
- 2. Stray losses or constant losses
- Stray losses: consist of (a) iron losses or core losses and (b) windage and friction losses.
- Iron losses: occurs in the core of the machine due to change of magnetic flux in the core.

 Consist of hysteresis loss and eddy current loss.
- <u>Hysteresis loss</u> depends upon the frequency, Flux density, volume and type of the core.

Losses/ /

<u>Hysteresis loss</u> depends upon the frequency, Flux density, volume and type of the core.

Eddy current losses: directly proportional to the flux density, frequency, thickness of the lamination.

Windage and friction losses are constant due to the opposition of wind and friction.

Applications

Shunt Generators:

- a. in electro plating
- b. for battery recharging
- c. as exciters for AC generators.

Series Generators:

- A. As boosters
- B. As lighting arc lamps

DC Motors

Converts Electrical energy into Mechanical energy

Construction: Same for Generator and motor

Working principle: Whenever a current carrying conductor is placed in the magnetic field, a force is set up on the conductor.

Back emf/

- The induced emf in the rotating armature conductors always acts in the opposite direction of the supply voltage.
- According to the Lenz's law, the direction of the induced emf is always so as to oppose the cause producing it.
- In a DC motor, the supply voltage is the cause and hence this induced emf opposes the supply voltage.

Classification of DC motors

DC motors are mainly classified into three types as listed below:

- Shunt motor
- Series motor
- Compound motor
 - Differential compound
 - Cumulative compound

Speed control of DC motors

According to the speed equation of a dc motor

 $N \propto Eb/\phi$

 ∞ V- Ia Ra/ ϕ

Thus speed can be controlled by-

Flux control method: By Changing the flux by controlling the current through the field winding.

Armature control method: By Changing the armature resistance which in turn changes the voltage applied across the armature

Flux control

Advantages of flux control:

- It provides relatively smooth and easy control
- Speed control above rated speed is possible
- As the field winding resistance is high the field current is small. Power loss in the external resistance is small. Hence this method is economical

Disadvantages:

- Flux can be increased only upto its rated value
- High speed affects the commutation, motor operation becomes unstable

Armature voltage control method

- The speed is directly proportional to the voltage applied across the armature .
- Voltage across armature can be controlled by adding a variable resistance in series with the armature

Potential divider control:

If the speed control from zero to the rated speed is required, by rheostatic method then the voltage across the armature can be varied by connecting rheostat in a potential divider arrangement.

Starters for DC motors

Needed to limit the starting current.

- 1. Two point starter
- 2. Three point starter
- 3. Four point starter

Applications:

Shunt Motor:

- Blowers and fans
- Centrifugal and reciprocating pumps
- Lathe machines
- Machine tools
- Milling machines
- Drilling machines

Applications:

Series Motor:

- **Cranes**
- Hoists, Elevators
- **Trolleys**
- Conveyors
- **Electric locomotives**

Applications:

Cumulative compound Motor:

- Rolling mills
- Punches
- **Shears**
- Heavy planers
- **Elevators**